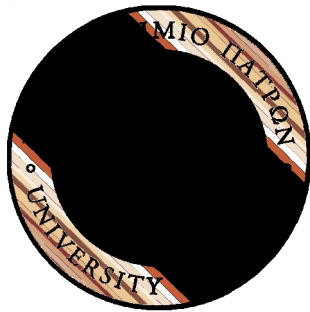
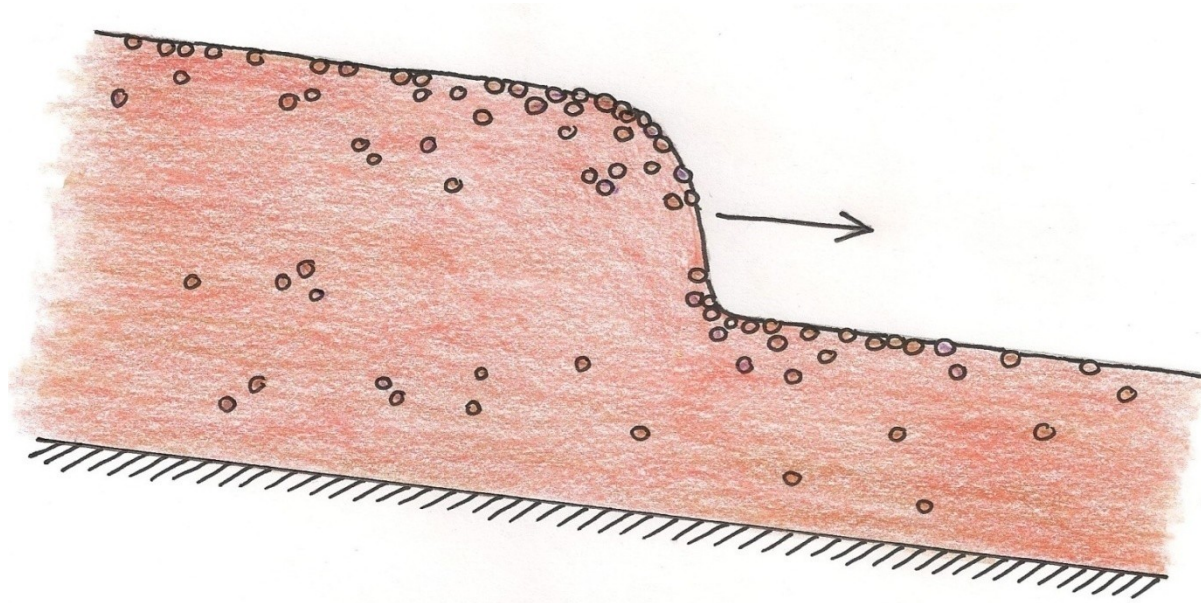


OK

The Granular Monoclinical Wave



Dimitris Razis
Giorgos Kanellopoulos
Ko van der Weele

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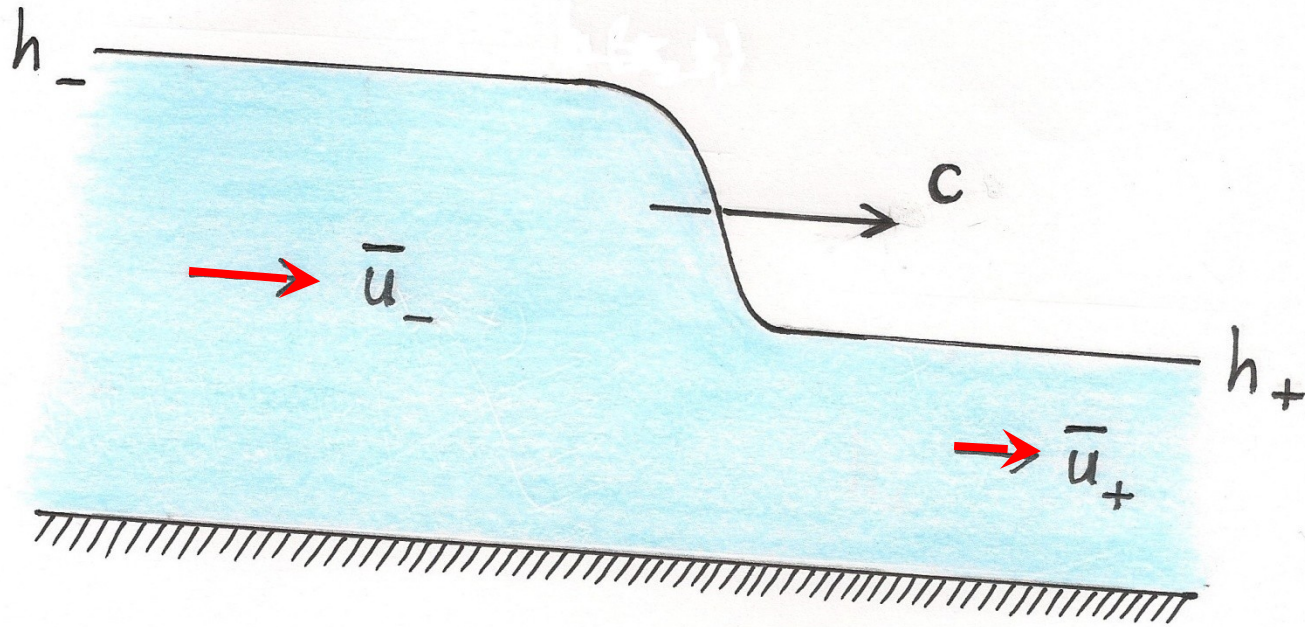
Monoclonal flood wave in water



well described by the Saint-Venant equations,
which are two coupled PDEs for

height of the water sheet $h(x,t)$ and $\bar{u}(x,t)$ depth-averaged velocity

Velocity profile:



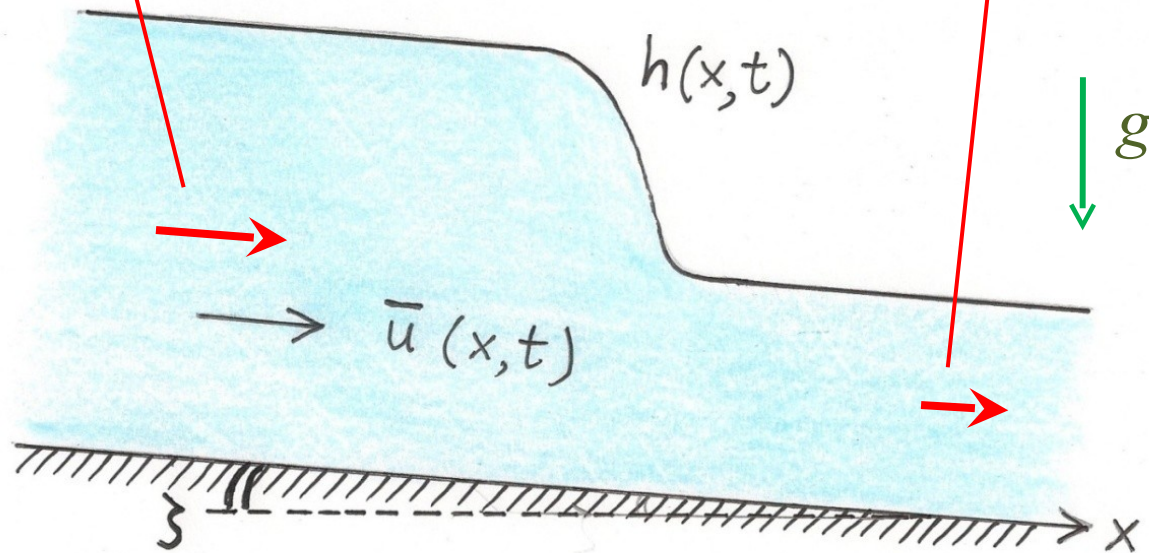
Depth-averaged velocity:

$$\bar{u}(x, t) = \frac{1}{h(x, t)} \int_0^{h(x, t)} u(x, z, t) dz$$

$$\text{Fr}_{in} = \frac{\bar{u}_-}{\sqrt{h_- g \cos \zeta}}$$

>

$$\text{Fr}_{downstream} = \frac{\bar{u}_+}{\sqrt{h_+ g \cos \zeta}}$$

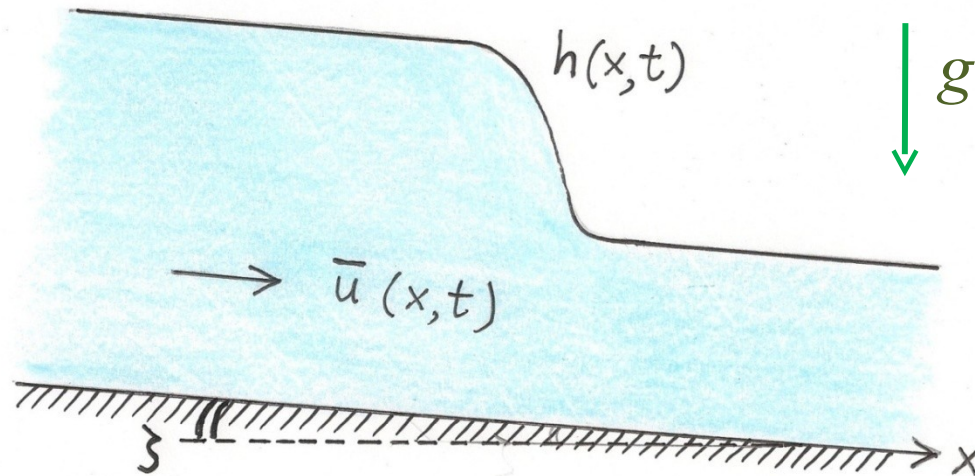


**Another important concept in this context:
the Froude number**

$$\text{Fr} = \text{Fr}(x,t) = \frac{\bar{u}(x,t)}{\sqrt{h(x,t) g \cos \zeta}}$$

inertial forces
vs. gravity

The Saint-Venant equations



1. Conservation of mass:
(continuity equation)

$$\frac{\partial h}{\partial t} + \frac{\partial (h\bar{u})}{\partial x} = 0$$

2. Momentum balance:

$$\underbrace{\frac{\partial}{\partial t}(h\bar{u}) + \frac{\partial}{\partial x}(h\bar{u}^2)}_{\text{momentum change}} = \underbrace{hg \sin \zeta}_{\text{gravity component in x-direction}} - \frac{\partial}{\partial x} \left(\frac{1}{2} gh^2 \cos \zeta \right) + \text{terms involving friction and viscosity}$$

↑ gradient of depth-averaged pressure

In fact, the Saint-Venant equations admit various types of waves:

also known in
granular flow

not yet observed
in granular flow

also in
granular flow

Gray & Edwards, JFM **755** (2014)

also in
granular flow

Boudet *et al.*, JFM **572** (2007)

Now we turn to granular matter



sand avalanches, landslides, etc.

Saint-Venant equations for granular flow

Mass conservation: $\partial_t h + \partial_x (h\bar{u}) = 0$

Momentum balance:

$$\partial_t (h\bar{u}) + \partial_x (h\bar{u}^2) = gh \sin \zeta - \frac{1}{2} \partial_x (gh^2 \cos \zeta) - \mu(h, \bar{u}) gh \cos \zeta + \nu \partial_x (h^{3/2} \partial_x \bar{u})$$

special granular
features:

↑
*friction with
the chute*

↑
*viscous-like
term*

Special granular features 1: the friction law

$$\partial_t (h\bar{u}) + \partial_x (h\bar{u}^2) = \text{the friction coefficient } \mu(h, \bar{u}) \text{ depends on } h \text{ and } \bar{u}$$
$$gh \sin \zeta - \frac{1}{2} \partial_x (gh^2 \cos \zeta) - \mu(h, \bar{u}) gh \cos \zeta + \nu \partial_x (h^{3/2} \partial_x \bar{u})$$

And also on the inclination ζ of the chute:

- In the case of **water**, an arbitrarily small *shear stress* is sufficient to put the fluid in motion.

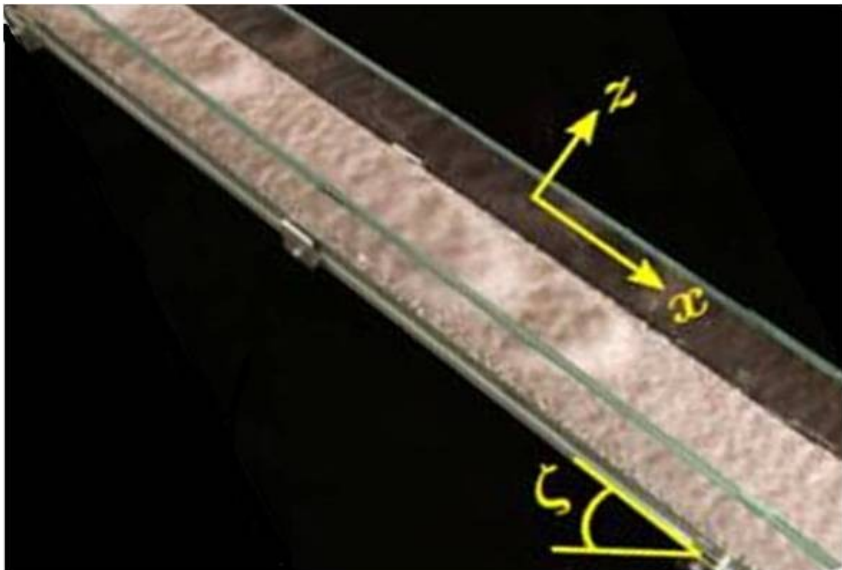
- **Sand**, however, remains motionless until the *shear stress* exceeds a certain threshold value => so the slope of the chute (ζ) has to exceed a critical value ζ_1 in order to make the sand flow. On the other hand, the slope must stay below a second critical value ζ_2 because otherwise the sand will rush down in an uncontrollable avalanche.

Only in the intermediate interval $\zeta_1 < \zeta < \zeta_2$ we can witness the balance between forces necessary for a steady flow.

Friction coefficient

Pouliquen and Forterre, J. Fluid Mech. **453** (2002)

$$\mu(h, \bar{u}) = \tan \zeta_1 + \frac{\tan \zeta_2 - \tan \zeta_1}{1 + (\beta / L) \frac{h^{3/2}}{\bar{u}} \sqrt{g \cos \zeta}} \quad (\text{for } Fr > \beta)$$



In our system:

$$\zeta_1 = 32.9^\circ$$

$$\zeta = 33.3^\circ$$

$$\zeta_2 = 42.0^\circ$$

$$\beta = 0.5$$

$$L = 1 \text{ mm}$$

Special granular features 2: the viscous term

$$\partial_t (h\bar{u}) + \partial_x (h\bar{u}^2) = gh \sin \zeta - \frac{1}{2} \partial_x (gh^2 \cos \zeta) - \mu(h, \bar{u}) gh \cos \zeta + \nu \partial_x (h^{3/2} \partial_x \bar{u})$$

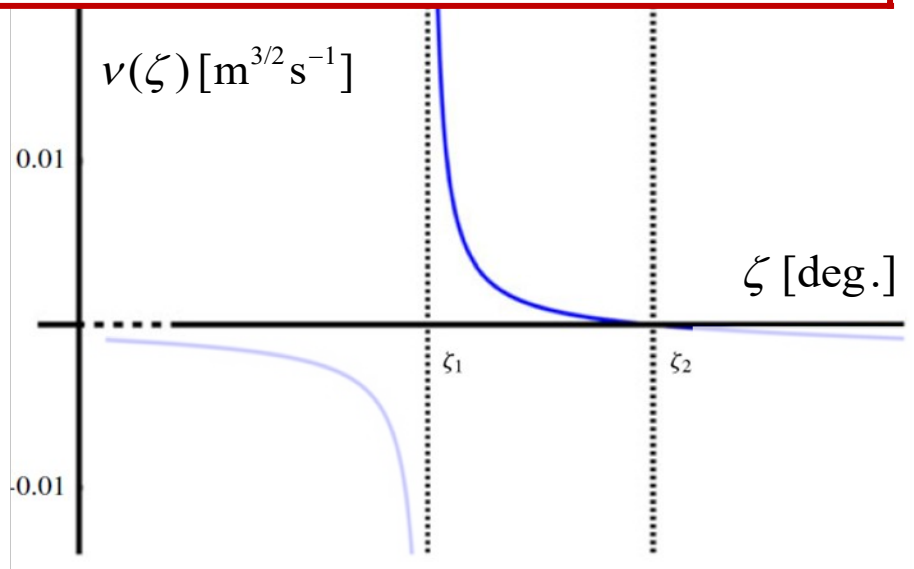
It plays a key role in preventing the waves from developing infinitely steep fronts.

This effective viscosity arises from the *normal stresses* in the granular sheet.

Gray and Edwards, J. Fluid Mech. **755** (2014)

$$\nu = \nu(\zeta) = \frac{2\sqrt{g}}{9} \left(\frac{L}{\beta} \right) \frac{\gamma(\zeta) \sin \zeta}{\sqrt{\cos \zeta}}$$

$$\text{where } \gamma(\zeta) = \frac{\tan \zeta_2 - \tan \zeta}{\tan \zeta - \tan \zeta_1}$$



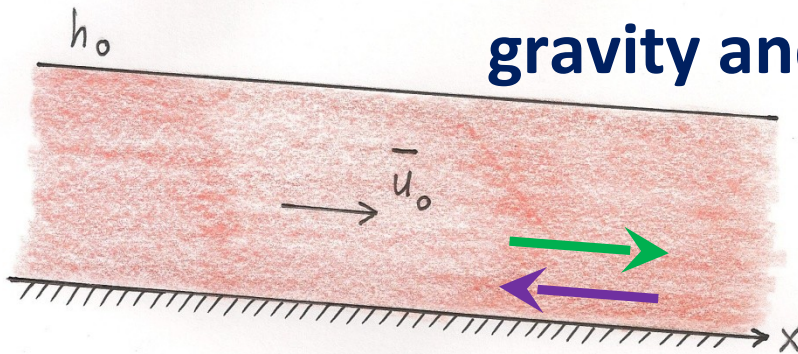
Basic solution: steady uniform flow

$$\cancel{\partial_t (h\bar{u})} + \cancel{\partial_x (h\bar{u}^2)} =$$

$$gh \sin \zeta - \mu(h, \bar{u}) gh \cos \zeta - \frac{1}{2} \cancel{\partial_x (gh^2 \cos \zeta)} + \nu \cancel{\partial_x (h^{3/2} \partial_x \bar{u})}$$

balance between the forces of gravity and friction:

$$\mu(h, \bar{u}) = \tan(\zeta)$$



$$\tan \zeta_1 + \frac{\tan \zeta_2 - \tan \zeta_1}{1 + (\beta / L) \frac{h^{3/2}}{\bar{u}} \sqrt{g \cos \zeta}} = \tan \zeta$$

$$\text{Fr} = \frac{\bar{u}_0}{\sqrt{h_0 g \cos \zeta}}$$

$$= \frac{\beta}{L \gamma(\zeta)} h$$

$$\bar{u}_0 = \frac{\beta \sqrt{g \cos \zeta}}{L \gamma(\zeta)} h_0^{3/2}$$

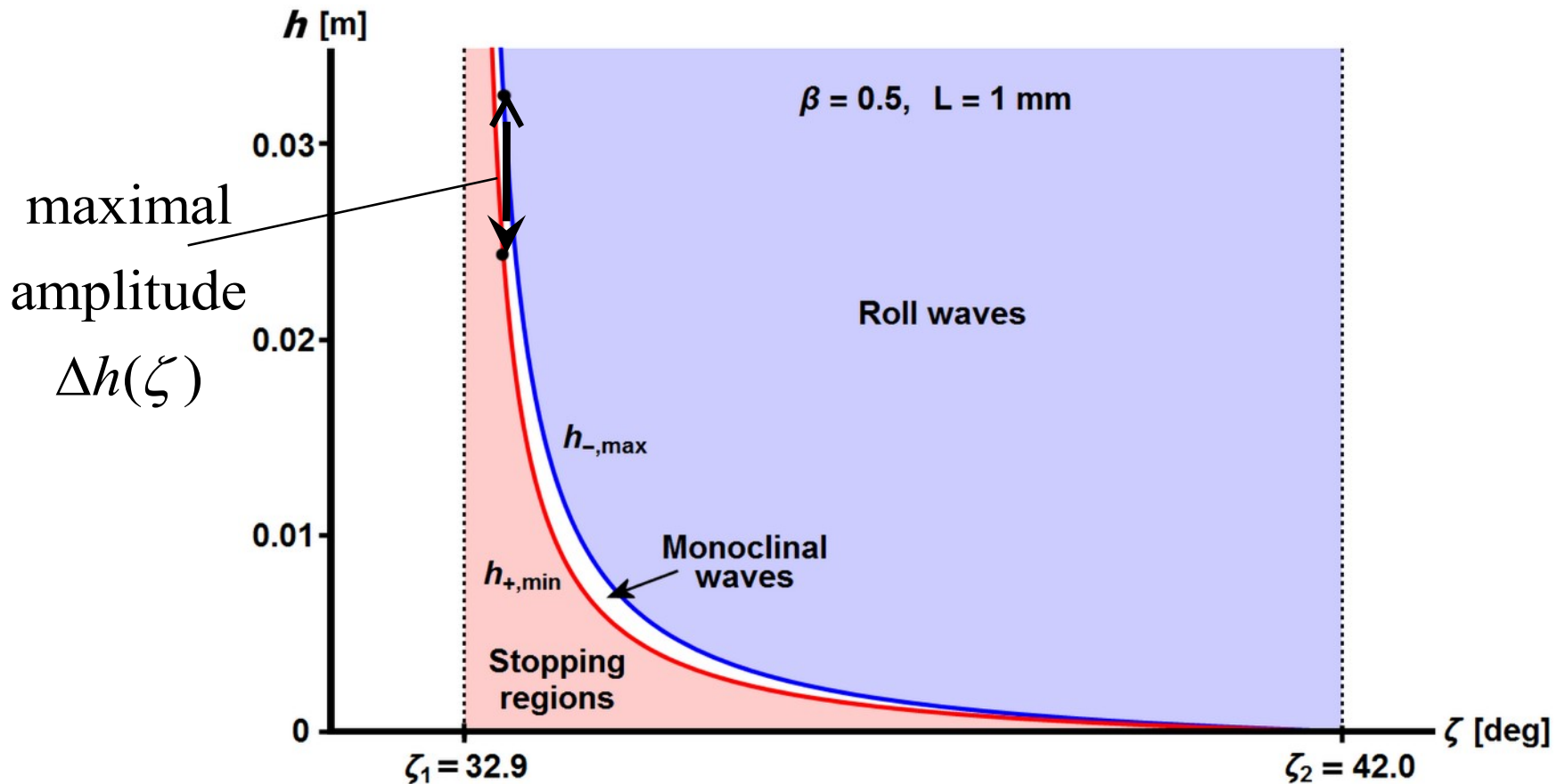
We expect monoclinal waves in the range:

Razis, Kanellopoulos & van der Weele, J. Fluid Mech. **843** (2018)

$$h_{+,min}(\zeta)$$

$$L\gamma(\zeta) \leq h \leq \frac{2L}{3\beta}\gamma(\zeta)$$

$$h_{-,max}(\zeta)$$

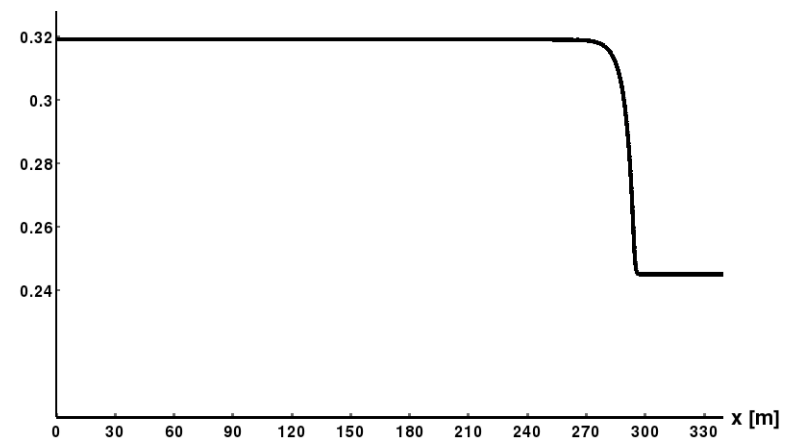


“The proof of the pudding is in the eating”

Numerical experiment



$h(x,t)$ [m]



$\bar{u}(x,t)$ [m/s]

Initial condition ($t = 0 \text{ s}$):

we

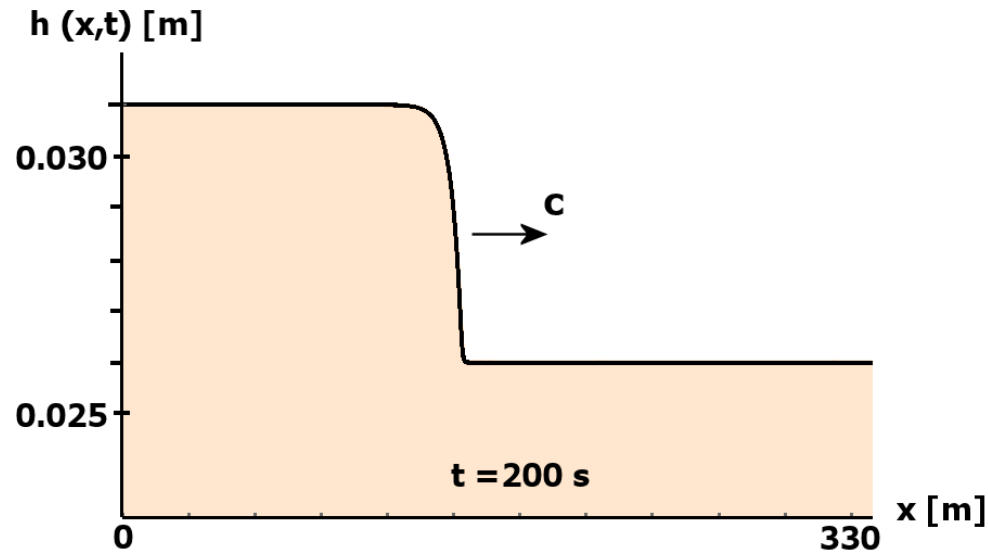
→ t

First-ever observation of a granular monoclinal wave

producing a genuine monoclinal wave

eld

ly,



J. Fluid Mech. (2018), vol. 843, pp. 810–846. © Cambridge University Press 2018
doi:10.1017/jfm.2018.149

810

The granular monoclinal wave

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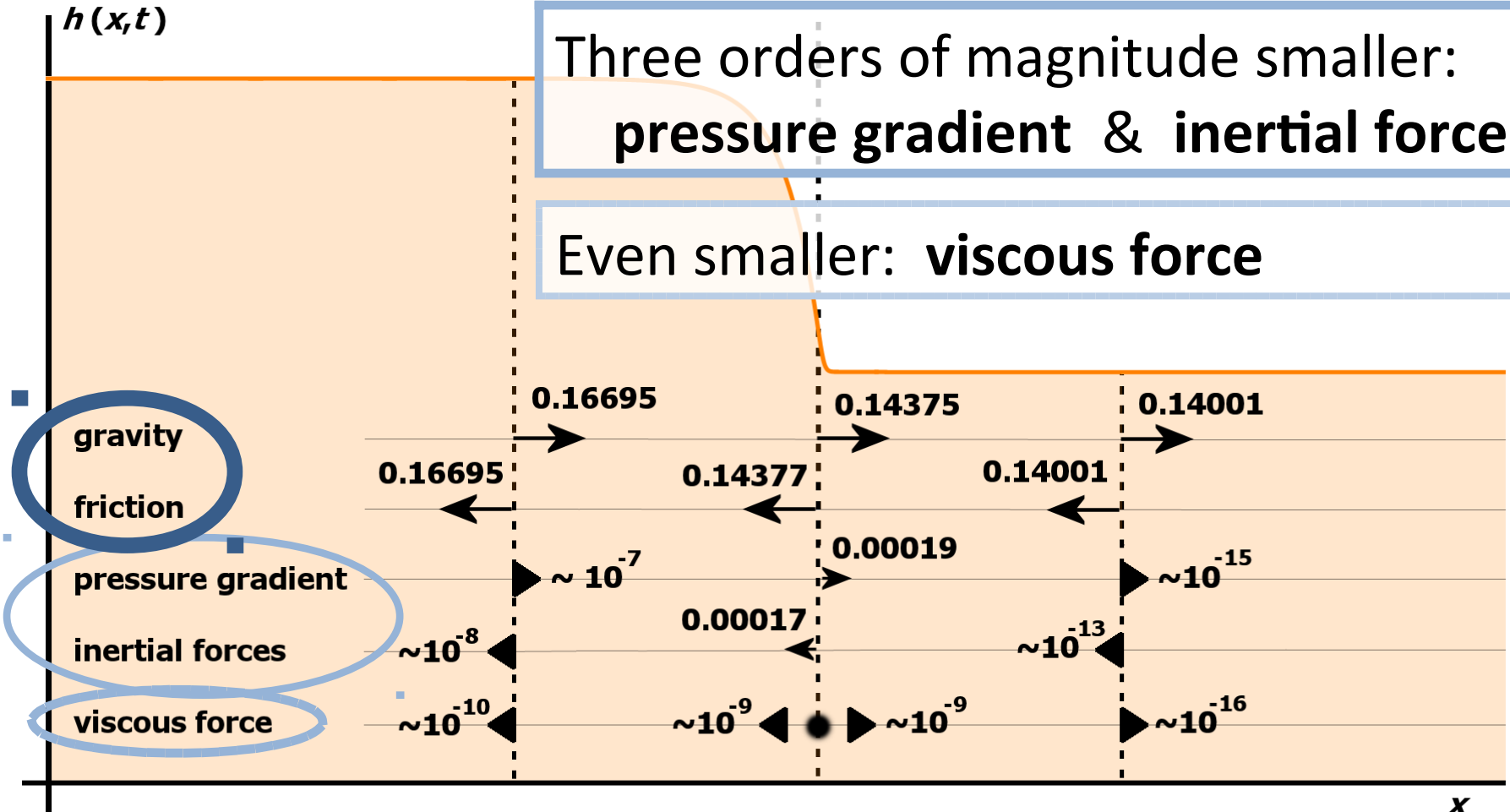
(Received 11 July 2017; revised 4 December 2017; accepted 1 February 2018)

Balance of forces in the monoclinal wave

Main players: **gravity & friction**

Three orders of magnitude smaller:
pressure gradient & inertial forces

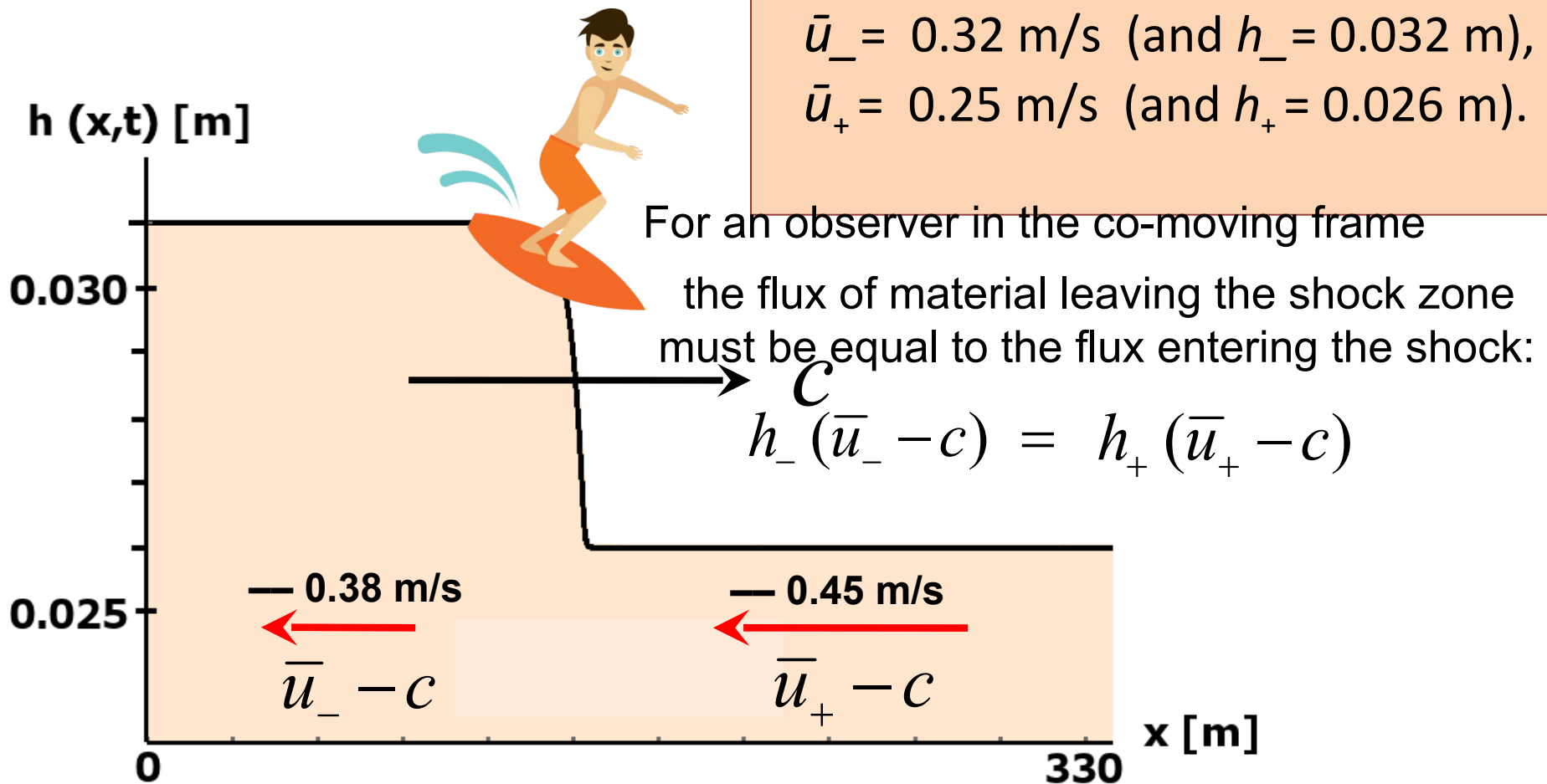
Even smaller: **viscous force**



Speed of the shock :

$$c = \frac{h_- \bar{u}_- - h_+ \bar{u}_+}{h_- - h_+}$$

Here: $c = 0.70$ m/s,
 $\bar{u}_- = 0.32$ m/s (and $h_- = 0.032$ m),
 $\bar{u}_+ = 0.25$ m/s (and $h_+ = 0.026$ m).



Travelling wave analysis

We introduce the travelling-wave variable

$$\xi = x - ct$$

and will be concerned with solutions of the form

$$h(x, t) = h(x - ct) = h(\xi)$$

$$\bar{u}(x, t) = \bar{u}(x - ct) = \bar{u}(\xi)$$

Then the mass conservation becomes:

$$-c \frac{dh}{d\xi} + \frac{d}{d\xi} (h\bar{u}) = 0$$

$$\text{or: } -c h' + (h\bar{u})' = 0$$

This can be integrated immediately:

$$-c h' + (h\bar{u})' = 0 \quad \Rightarrow \quad -ch + h\bar{u} = \boxed{-K} \quad \text{integration constant}$$



$$K = h(c - \bar{u})$$



**constant flux
observed in the
co-moving frame**

With this ($\bar{u} = c - K h^{-1}$ and hence $\bar{u}' = K h^{-2} h'$, etc.) we can eliminate \bar{u} and its derivatives from the momentum balance:

$$\frac{\nu K}{h^{3/2}} h'' - \frac{\nu K}{2h^{5/2}} (h')^2 + \left(\frac{K}{h^3} - g \cos \zeta \right) h' + g \sin \zeta - \mu(h) g \cos \zeta = 0$$

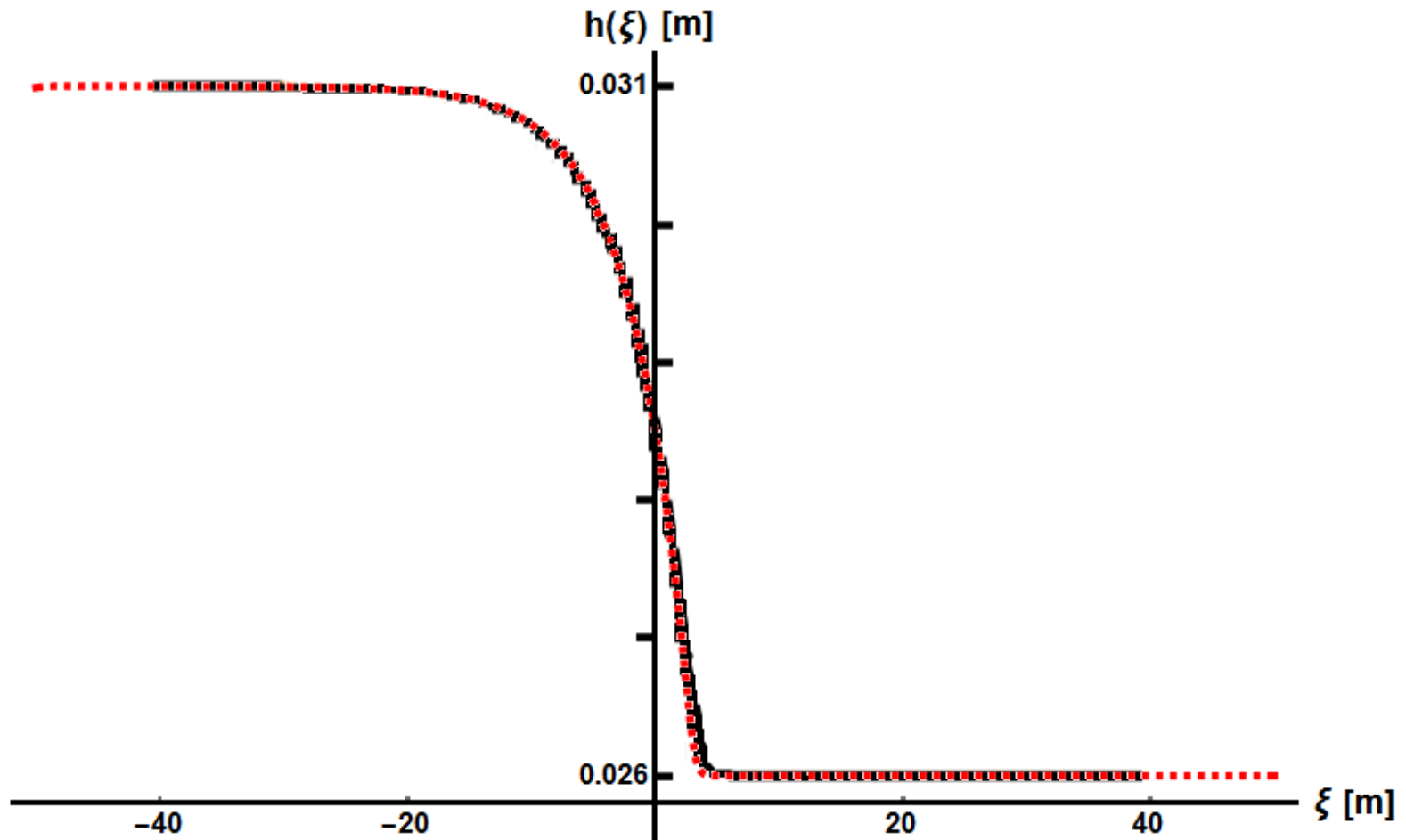
One single second-order ODE for $h(\xi)$!!

Note that with $\bar{u} = c - K h^{-1}$ also the friction coefficient $\mu(h, \bar{u})$ has become a function of h alone:

$$\mu(h) = \tan(\zeta_1) + \frac{\tan(\zeta_2) - \tan(\zeta_1)}{1 + \beta L^{-1} \sqrt{g \cos(\zeta)} h^{5/2} / (ch - K)}$$

This ODE (with the proper boundary conditions) gives *all* granular waveforms travelling at constant speed.

In particular also the **monoclinal wave**:



Dimensionless form of the ODE

By measuring all length scales (h and ξ) in terms of the thickness h_- of the incoming sheet, and c in terms of the corresponding velocity \bar{u}_- , we obtain:

$$\frac{d^2 \tilde{h}}{d\tilde{\xi}^2} - \frac{1}{2\tilde{h}} \left(\frac{d\tilde{h}}{d\tilde{\xi}} \right)^2 + \frac{R_{in} \tilde{h}^{3/2}}{F_{in}^2 (\tilde{c} - 1)} \left[\left(\frac{F_{in}^2 (\tilde{c} - 1)^2}{\tilde{h}^3} - 1 \right) \frac{d\tilde{h}}{d\tilde{\xi}} + \tan \zeta - \mu(\tilde{h}) \right] = 0$$

where R_{in} and F_{in} are the Reynolds and Froude number of the incoming sheet:

$$R_{in} = \frac{\bar{u}_- h_-^{1/2}}{\nu(\zeta)}, \quad F_{in} = \frac{\bar{u}_-}{\sqrt{h_- g \cos \zeta}}$$

$$\tilde{h} = \frac{h}{h_-}$$

$$\tilde{\xi} = \frac{\xi}{h_-}$$

$$\tilde{c} = \frac{c}{\bar{u}_-} \propto c h_-^{-3/2}$$

Dynamical Systems approach

Our second-order ODE

$$\frac{d^2 \tilde{h}}{d\tilde{\xi}^2} - \frac{1}{2\tilde{h}} \left(\frac{d\tilde{h}}{d\tilde{\xi}} \right)^2 + \frac{R_{in} \tilde{h}^{3/2}}{F_{in}^2 (\tilde{c} - 1)} \left[\left(\frac{F_{in}^2 (\tilde{c} - 1)^2}{\tilde{h}^3} - 1 \right) \frac{d\tilde{h}}{d\tilde{\xi}} + \tan \zeta - \mu(\tilde{h}) \right] = 0$$

can also be written as a system of 2 first-order equations:

$$\begin{cases} \frac{d\tilde{h}}{d\tilde{\xi}} = \tilde{s} = f(\tilde{h}, \tilde{s}) \\ \frac{d\tilde{s}}{d\tilde{\xi}} = \frac{\tilde{s}^2}{2\tilde{h}} - \frac{R_{in} \tilde{h}^{3/2}}{F_{in}^2 (\tilde{c} - 1)} \left[\left(\frac{F_{in}^2 (\tilde{c} - 1)^2}{\tilde{h}^3} - 1 \right) \tilde{s} + \tan \zeta - \mu(\tilde{h}) \right] = g(\tilde{h}, \tilde{s}) \end{cases}$$

Fixed points:

fixed points correspond to
flat regions of the flow

$$\left\{ \begin{array}{l} \frac{d\tilde{h}}{d\tilde{\xi}} = 0 \\ \frac{d\tilde{s}}{d\tilde{\xi}} = 0 \end{array} \right. \longrightarrow \begin{array}{l} f(\tilde{h}, \tilde{s}) = \tilde{s} = 0 \\ g(\tilde{h}, \tilde{s}) = g(\tilde{h}, 0) = 0 \end{array}$$

which translates to $\mu(\tilde{h}) = \tan \zeta$

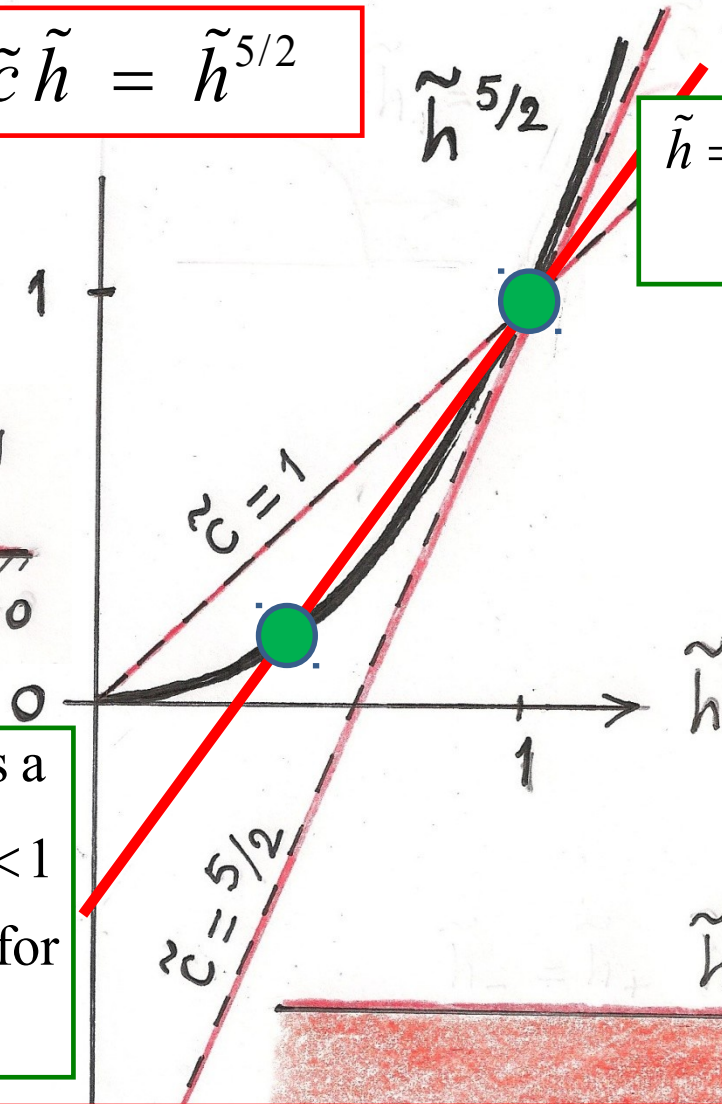
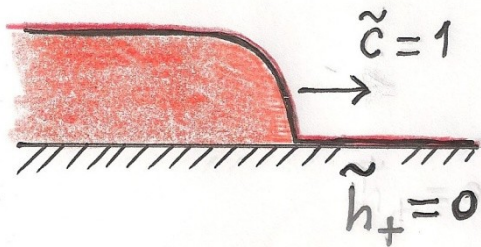
Of course!

(the familiar balance between friction
and gravity in uniform flow regions),

or equivalently:

$$1 - \tilde{c} + \tilde{c} \tilde{h} = \tilde{h}^{5/2}$$

$$\text{Solving } 1 - \tilde{c} + \tilde{c} \tilde{h} = \tilde{h}^{5/2}$$



$\tilde{h} = 1$ is **always** a solution
(for every \tilde{c})

For $1 < \tilde{c} < 2.5$ there is a second solution $0 < \tilde{h}_+ < 1$ (exactly what is needed for a monoclinal wave)

\Rightarrow For $1 < \tilde{c} < 2.5$ the system has *two* fixed points:
 $(\tilde{h}, \tilde{s}) = (\tilde{h}_+, 0)$ and $(\tilde{h}, \tilde{s}) = (\tilde{h}_-, 0) = (1, 0)$

Stability of the fixed points

is determined by the eigenvalues of the Jacobian matrix at the fixed points:

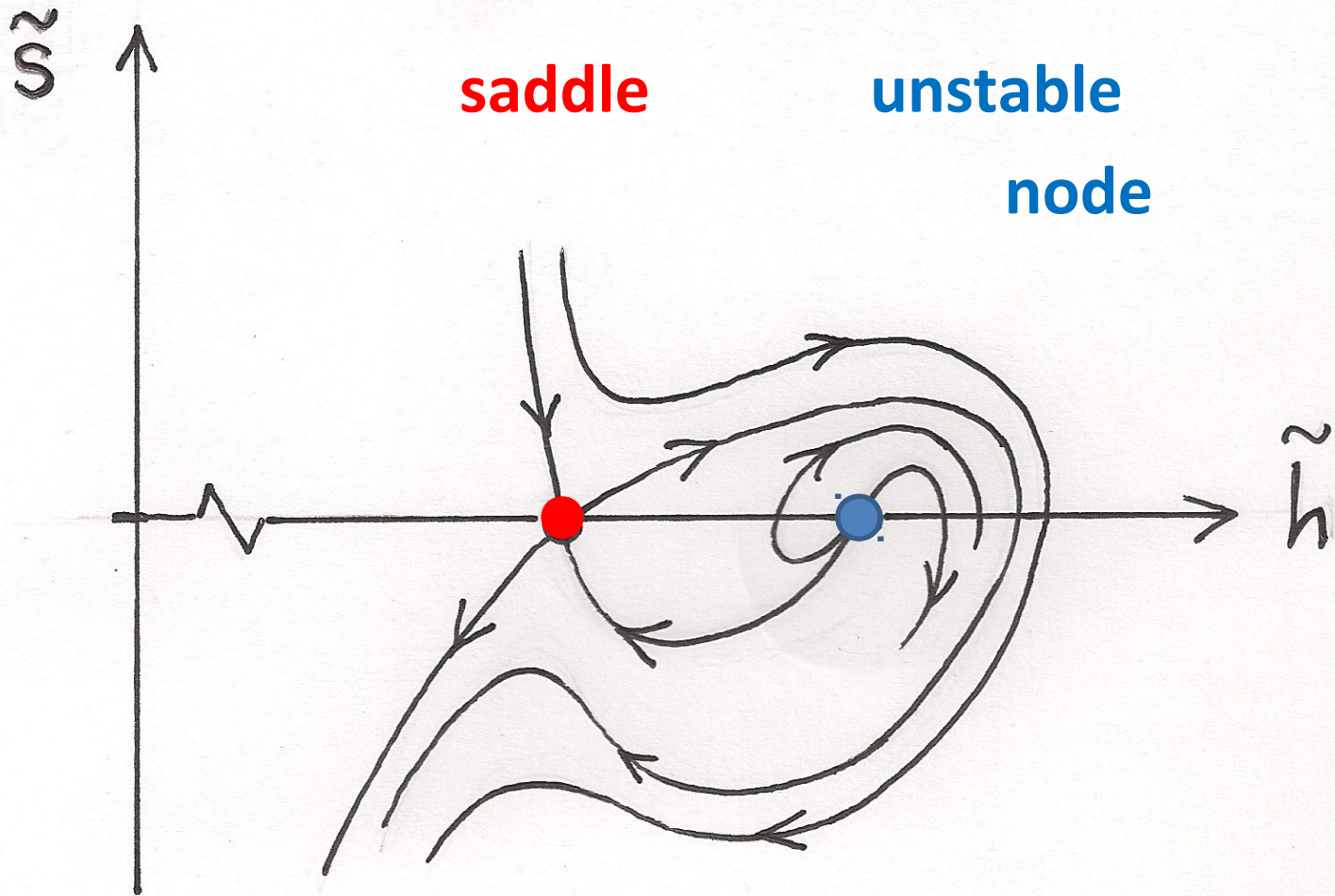
$$J = \begin{pmatrix} \frac{\partial f(\tilde{h}, \tilde{s})}{\partial \tilde{h}} & \frac{\partial f(\tilde{h}, \tilde{s})}{\partial \tilde{s}} \\ \frac{\partial g(\tilde{h}, \tilde{s})}{\partial \tilde{h}} & \frac{\partial g(\tilde{h}, \tilde{s})}{\partial \tilde{s}} \end{pmatrix}_{(\tilde{h}_{\pm}, 0)} = \begin{pmatrix} 0 & 1 \\ \frac{\partial g(\tilde{h}, \tilde{s})}{\partial \tilde{h}} & \frac{\partial g(\tilde{h}, \tilde{s})}{\partial \tilde{s}} \end{pmatrix}_{(\tilde{h}_{\pm}, 0)}$$

For the parameter values considered here we find that:

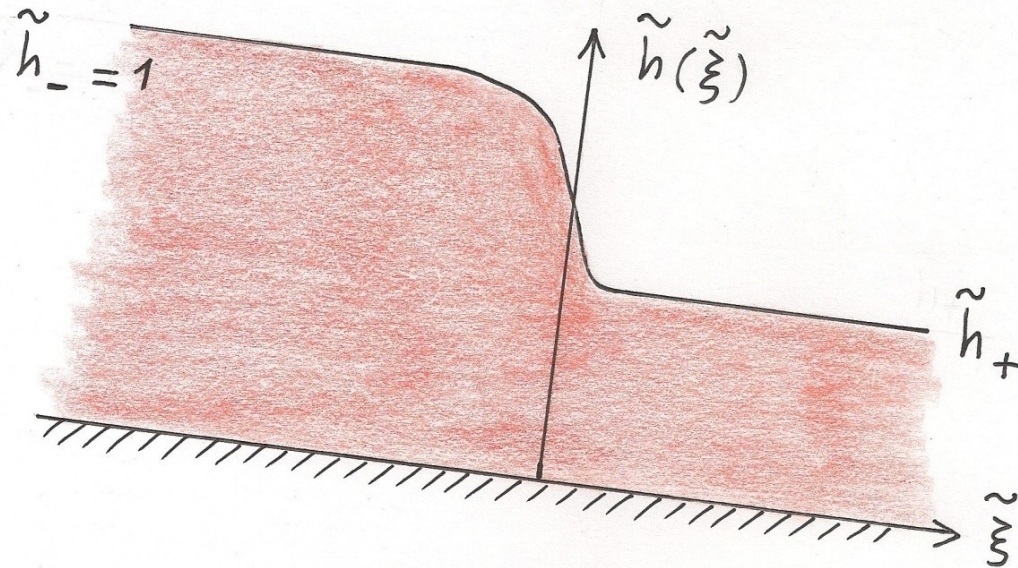
$(\tilde{h}_{+}, 0)$ is a saddle point

$(\tilde{h}_{-}, 0) = (1, 0)$ is an unstable node

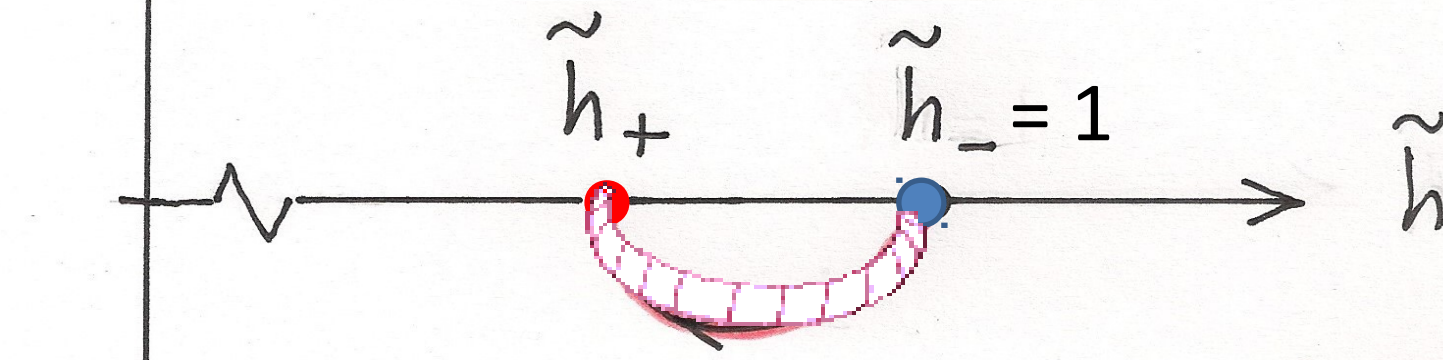
Phase portrait



The heteroclinic



o the
ed points:



So we have arrived at a **dynamical systems view** of the granular monoclinal wave

**in the co-moving frame,
in dimensionless form.**

What more can
one ask for!

Concluding remarks

- 1. The elusive granular monoclinal wave has been found.**
 - Thus completing the 1-1 correspondence between the “Saint-Venant” waveforms in water and sand.**

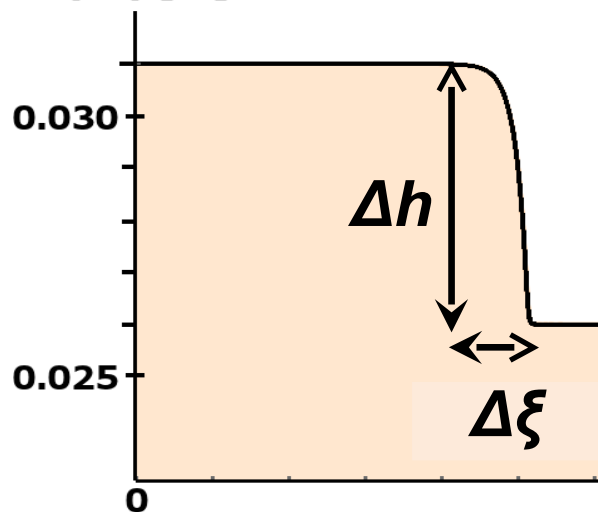
Concluding remarks

2. How feasible will it be to detect a granular monoclinal wave in practice?

→ The experimental challenge is:

«How to maximize the ratio $\Delta h/\Delta\xi$ »

$h(x,t)$ [m]



Here: $\Delta h = 0.006$ m (= 6 mm)
 $\Delta\xi \approx 30$ m

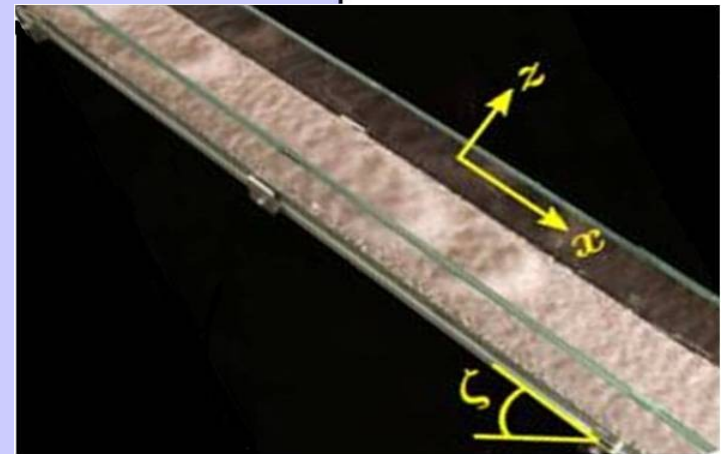
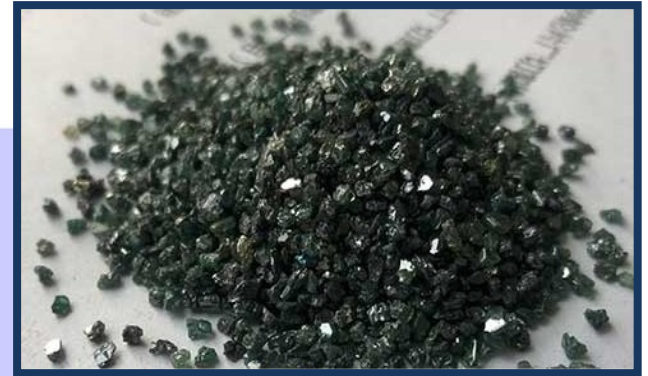
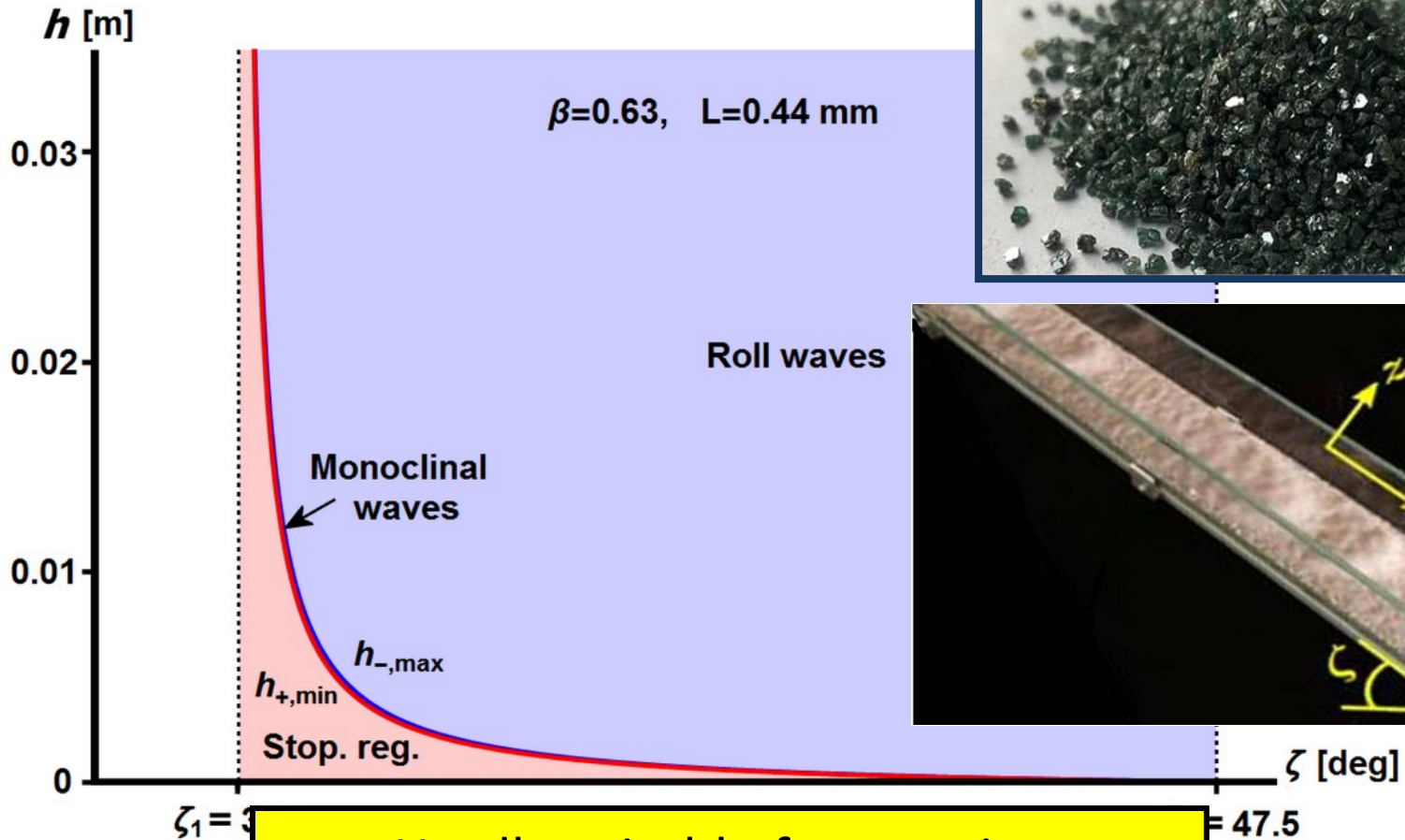
→ ratio $\Delta h/\Delta\xi \approx 2 \cdot 10^{-4}$

This plot is for our “typical parameter values”. Let us also have a look at two actual experimental set-ups.

Carborundum particles on the Manchester chute:

$$\beta = 0.63, L = 0.44 \text{ mm}, \zeta_1 = 31.1^\circ \text{ and } \zeta_2 = 47.5^\circ$$

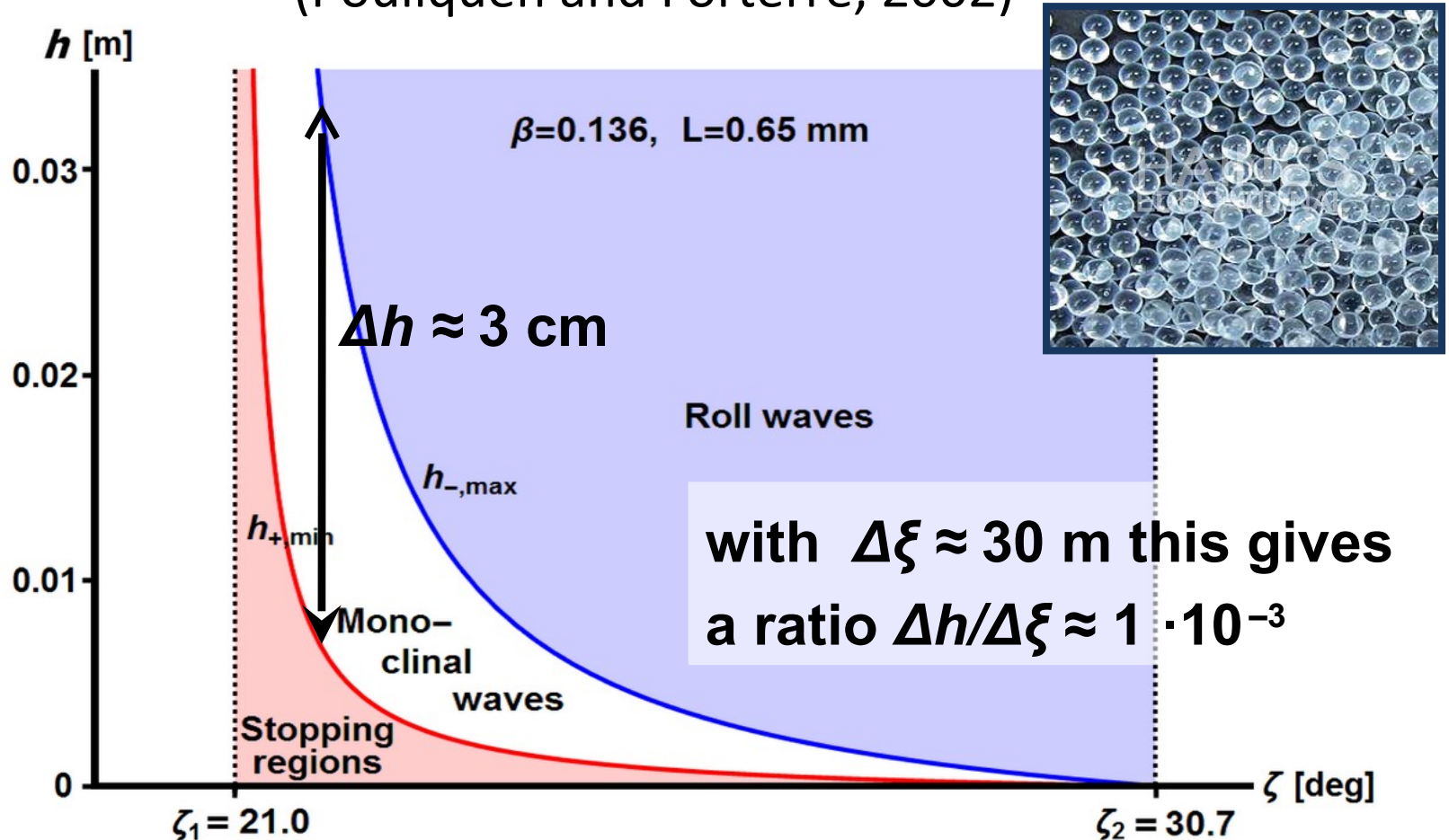
(Edwards *et al.*, 2017)



Hardly suitable for spotting
monoclinal waves

Smooth glass beads on the chute in Marseille:

$\beta = 0.136$, $L = 0.65$ mm, $\zeta_1 = 21.0^\circ$ and $\zeta_2 = 30.7^\circ$
(Pouliquen and Forterre, 2002)



with $\Delta\xi \approx 30$ m this gives
a ratio $\Delta h/\Delta\xi \approx 1 \cdot 10^{-3}$

Still challenging, but not impossible

Concluding remarks

3. Last but not least, the Dynamical Systems approach can also be used to analyze the other waveforms.

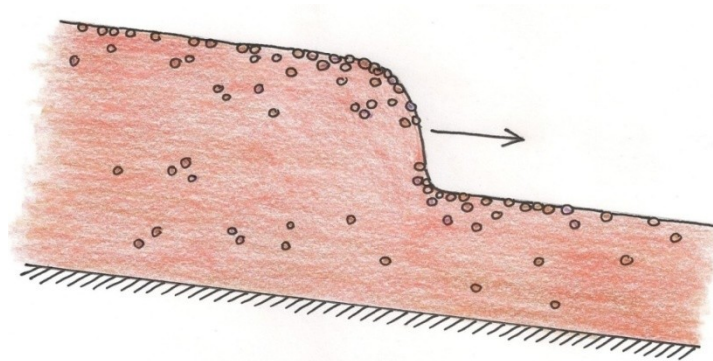
→ **Roll waves**

→ **Rising waves / granular jumps**

Next time, I hope!

Thank you for your attention

- D. Razis, G. Kanellopoulos & K. van der Weele, *The granular monoclinical wave*, J. Fluid Mech. 843 (2018).
- D. Razis, G. Kanellopoulos & K. van der Weele, *From monoclinical flood waves to roll waves and beyond: a phase-plane view of granular chute flow* (preprint, 2018).
- D. Razis, A.N. Edwards, J.M.N.T. Gray & K. van der Weele, *Arrested coarsening of granular roll waves*, Phys. Fluids 26 (2014).



The End



OK or K.O.?